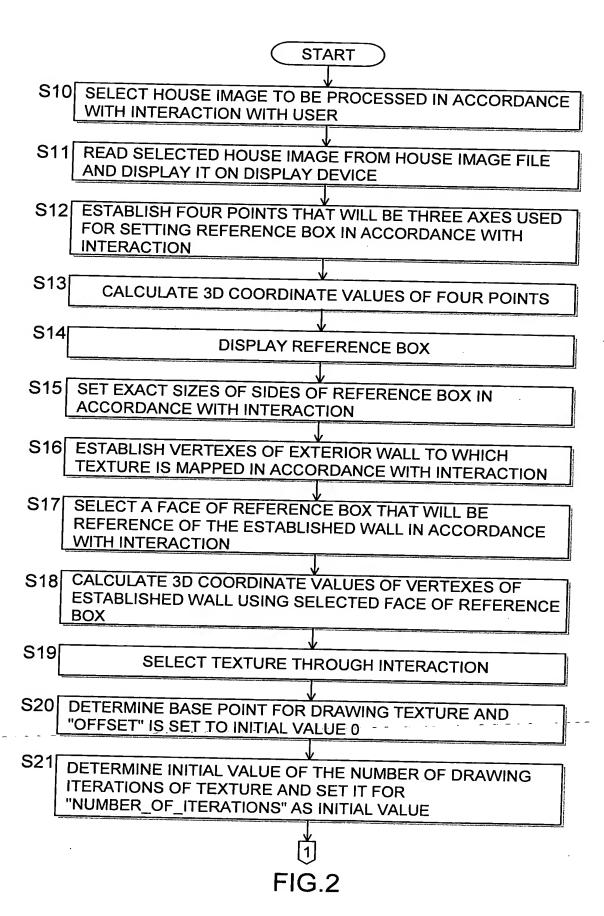
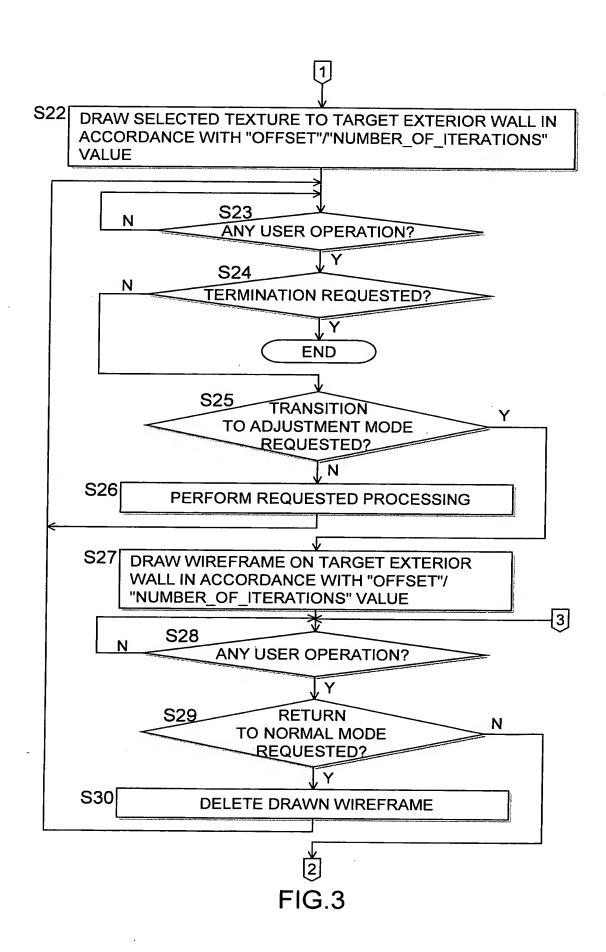


FIG. 1





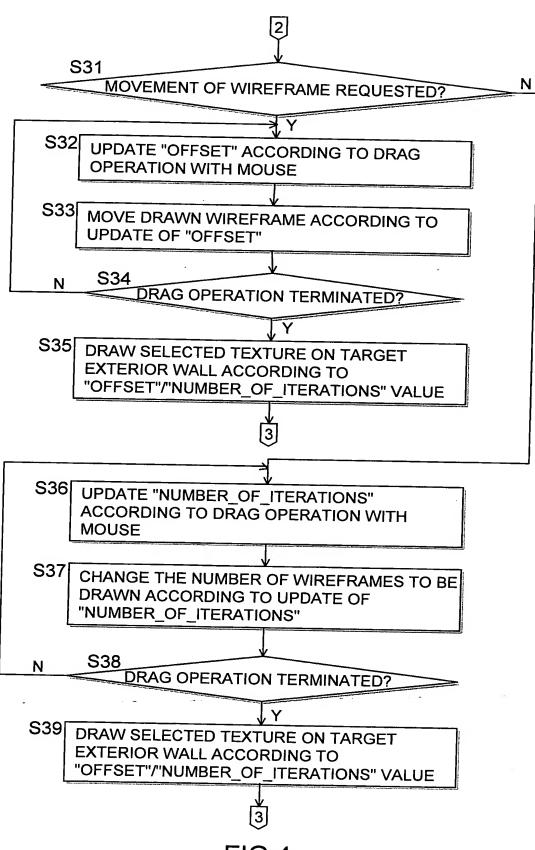


FIG.4

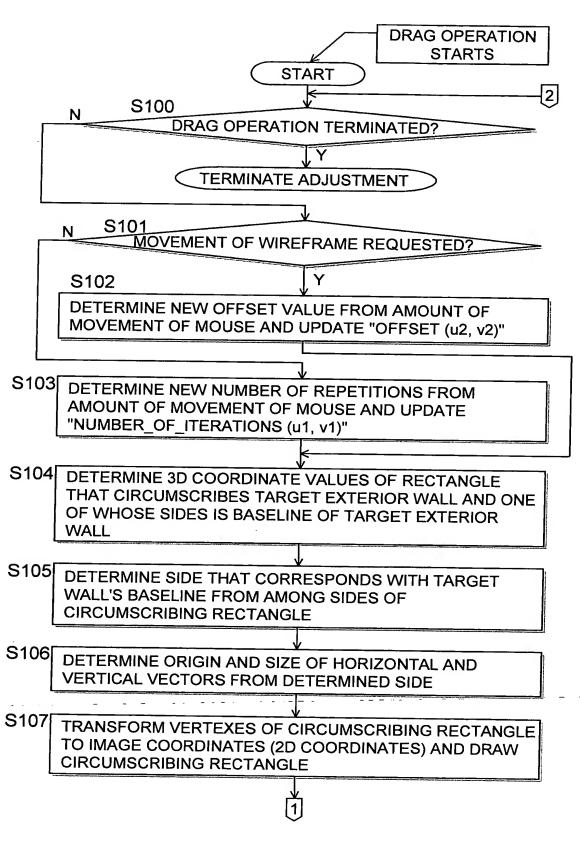


FIG.5

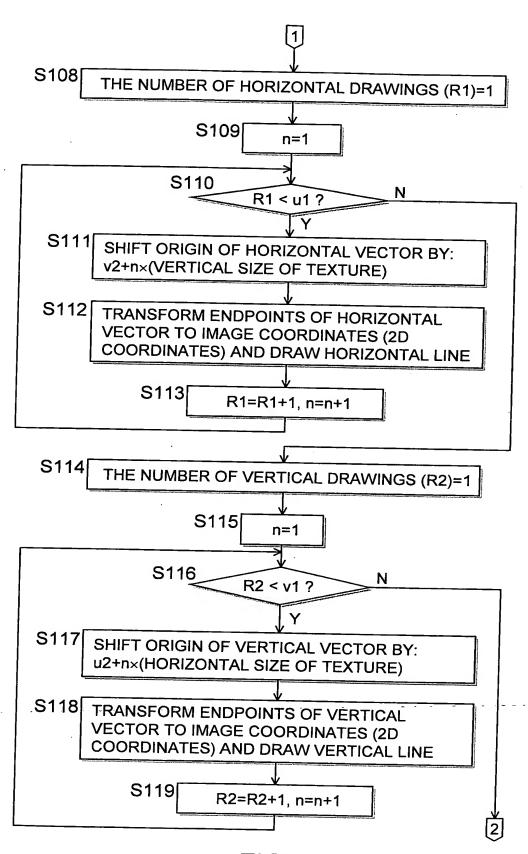
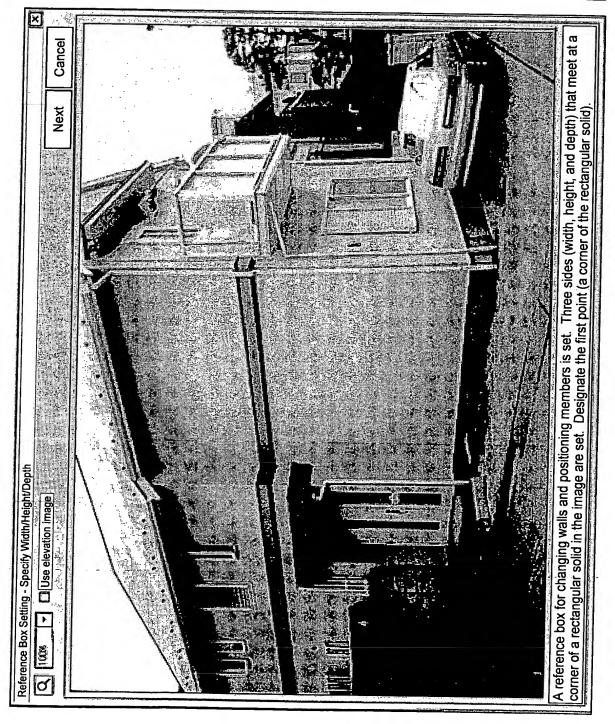
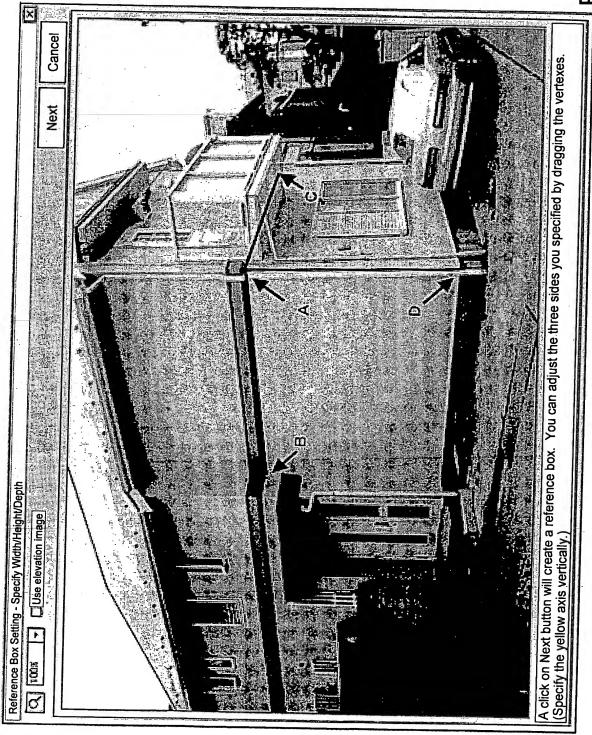
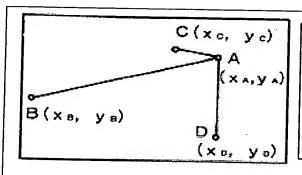


FIG.6







f: value corresponding to a focal length

Z_A: initial value

In an actual 3D space, AB and AC, AB and AD, and AC and AD will be each orthogonal to one another.

$$\begin{pmatrix} X \\ Y \\ Z \end{pmatrix} = \frac{Z}{f} \begin{pmatrix} x \\ y \\ f \end{pmatrix} \cdots (1)$$

$$\overrightarrow{AB} \cdot \overrightarrow{AC} = 0 \text{ (inner product is 0)}$$

$$\begin{bmatrix} \frac{Z_B}{f} \begin{pmatrix} x_B \\ y_B \\ f \end{pmatrix} - \frac{Z_A}{f} \begin{pmatrix} x_A \\ y_A \\ f \end{pmatrix} \cdot \begin{bmatrix} \frac{Z_C}{f} \begin{pmatrix} x_C \\ y_C \\ f \end{pmatrix} - \frac{Z_A}{f} \begin{pmatrix} x_A \\ y_A \\ f \end{pmatrix} = 0$$

$$(2)$$

Similarly,
$$AB \cdot AD = 0 \qquad \cdots \qquad (3)$$
Similarly,
$$AC \cdot AD = 0 \qquad \cdots \qquad (4)$$

Unknowns Z_B , Z_C , and Z_D are determined from the three equations (2), (3) and (4) and the values are substituted to the equation (1).

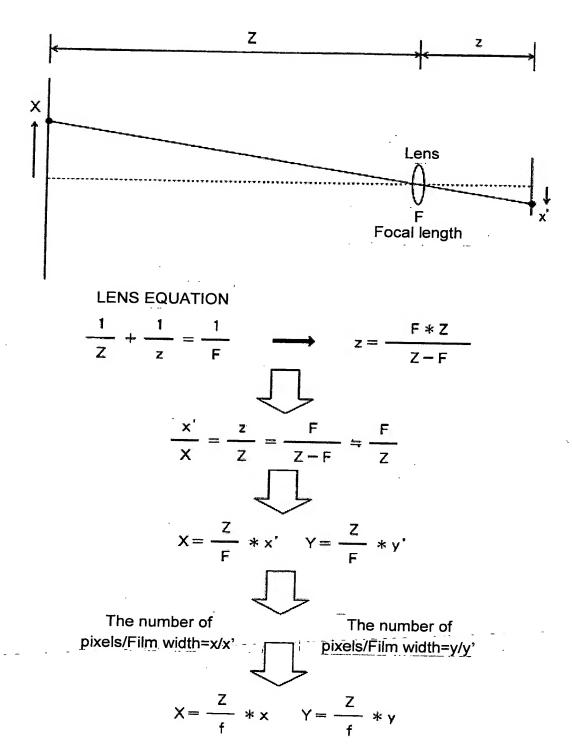
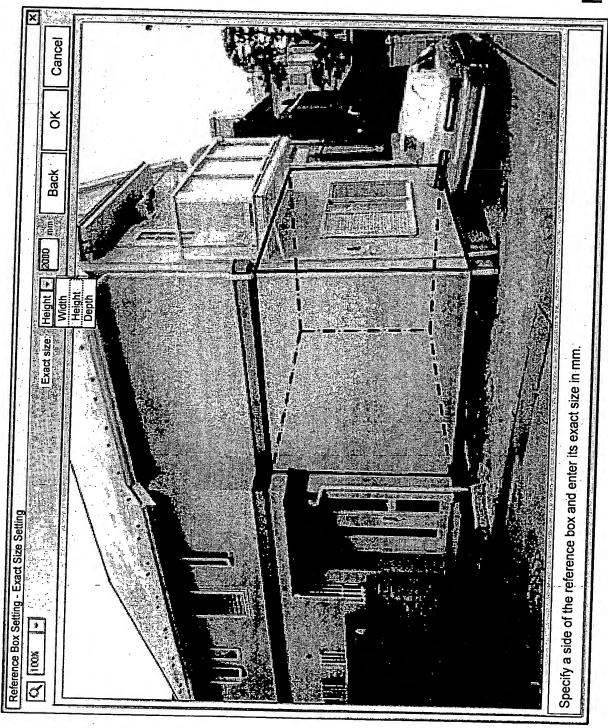
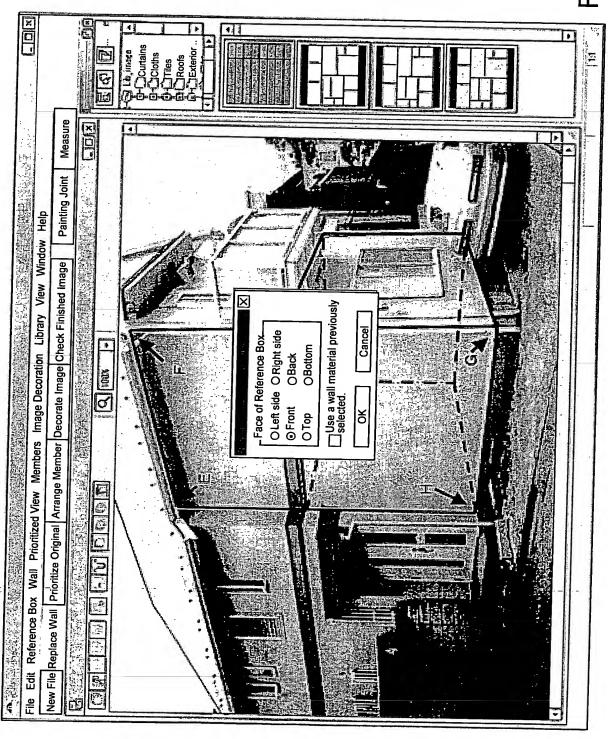
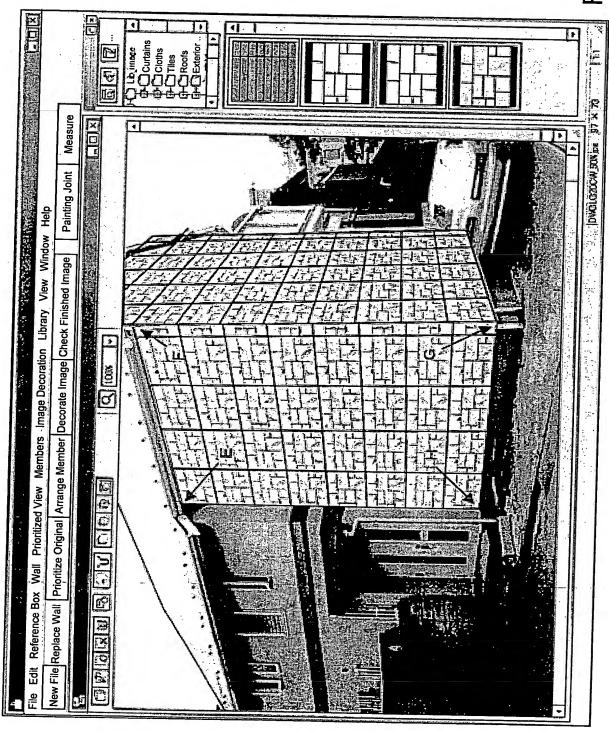


FIG.10

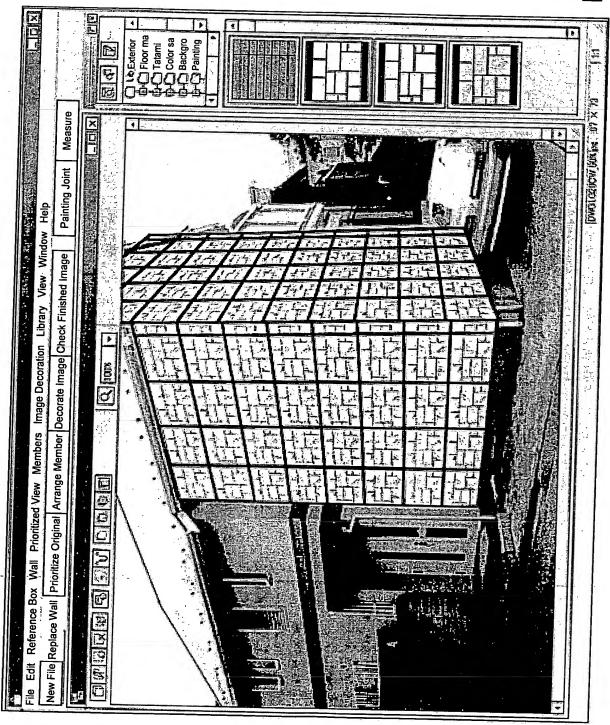


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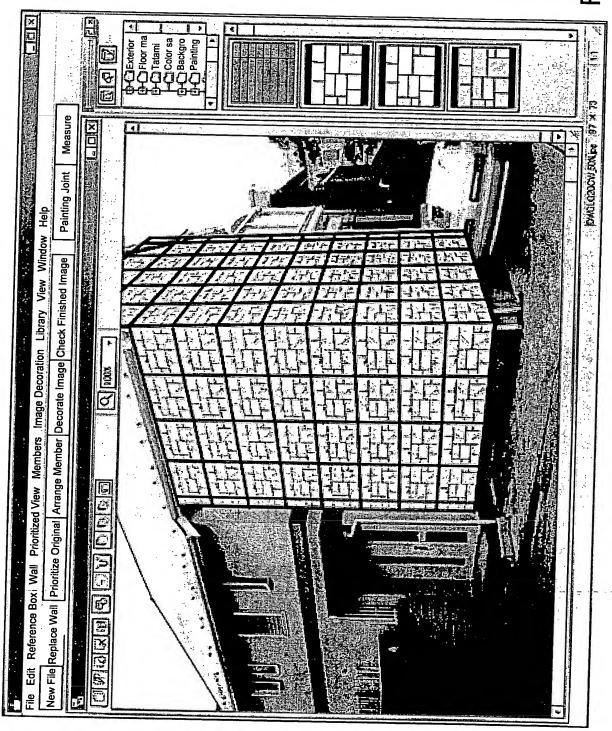




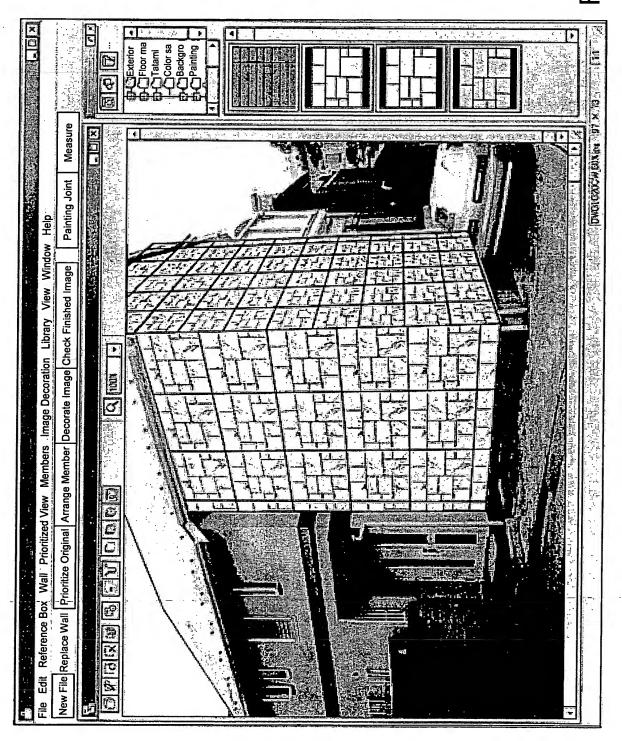
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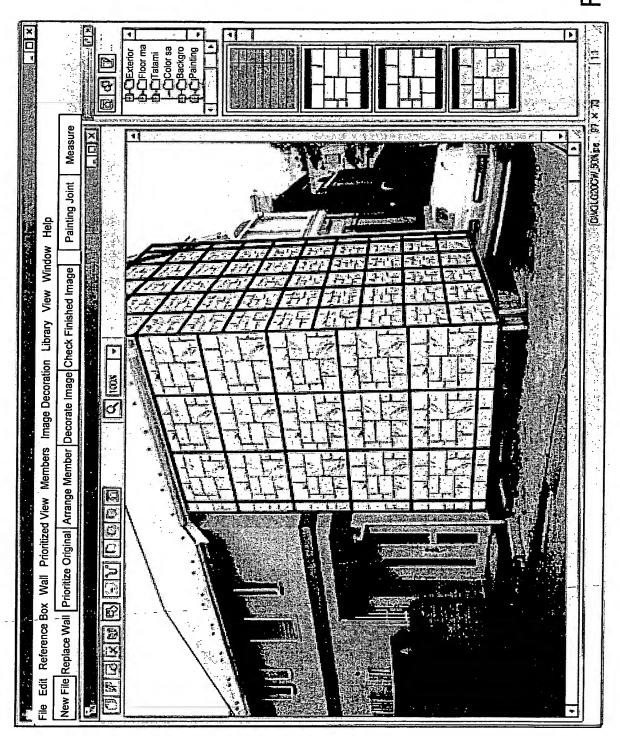


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